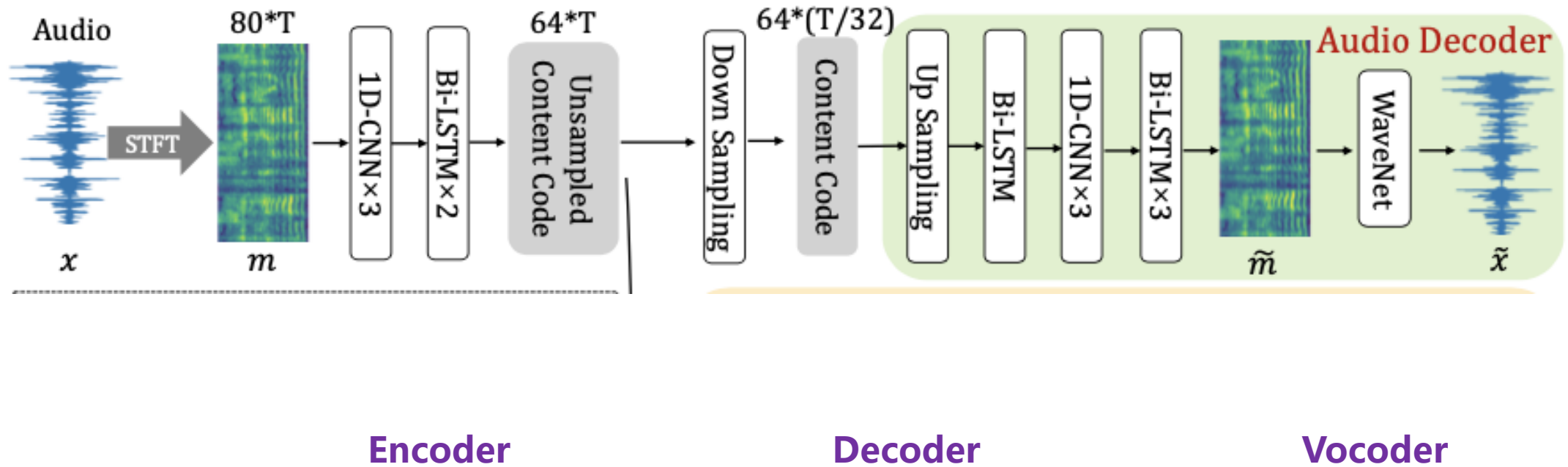


Cycle-Loss based Exemplar Autoencoder for Voice Conversion

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2021.11.10

Exemplar Autoencoder

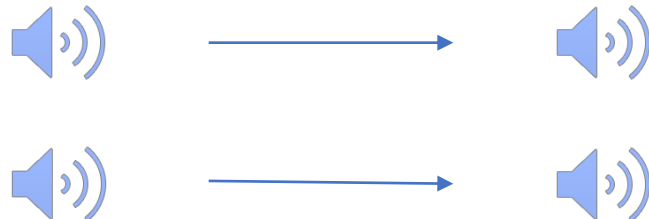


Compressibility of Audio Speech

- Speech contains two types of information: $x = f(s, w)$
 - (i) content (large variance) (ii) style (little variance)
- Human Acoustics:
 - $Error(f(s_1, w_0), f(s_2, w_0)) \leq Error(f(s_1, w_0), f(s_2, w)), \forall w \in W$
- Autoencoder for Style Transfer:
 - $D(E(\hat{x})) \approx \arg\min_{t \in M} Error(t, \hat{x}) = \arg\min_{t \in M} Error(t, f(s_1, w)) \approx f(s_2, w)$
 - M is the manifold spanning a particular style s_2 .
 - Given sufficiently small bottlenecks, autoencoders can project out-of-sample points into the input subspace, so as to minimize the reconstruction error of the output.

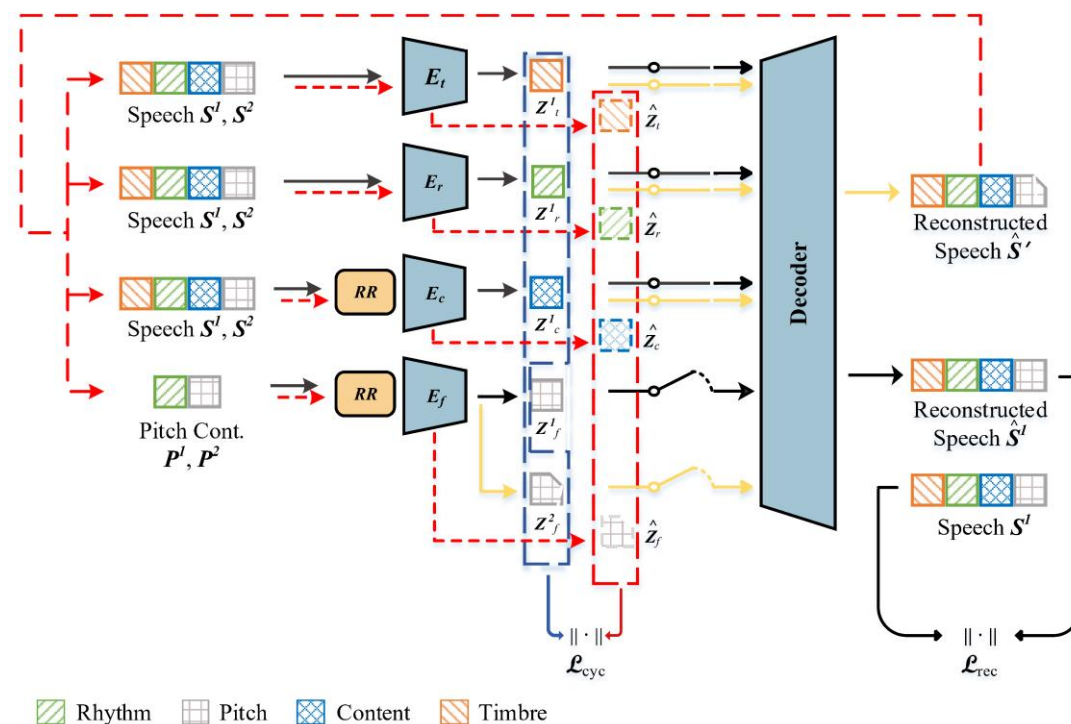
Properties

- Pros
 - A simple autoencoder framework(CNN+BI-LSTM)
 - Data-efficient and zero-shot
 - given a target speech with a particular, learn an autoencoder specific to that target speech
- Cons
 - Bad performance on cross-gender task
 - the content from the bottleneck and the speaker style from the weights are not purely factorized.



CycleFlow

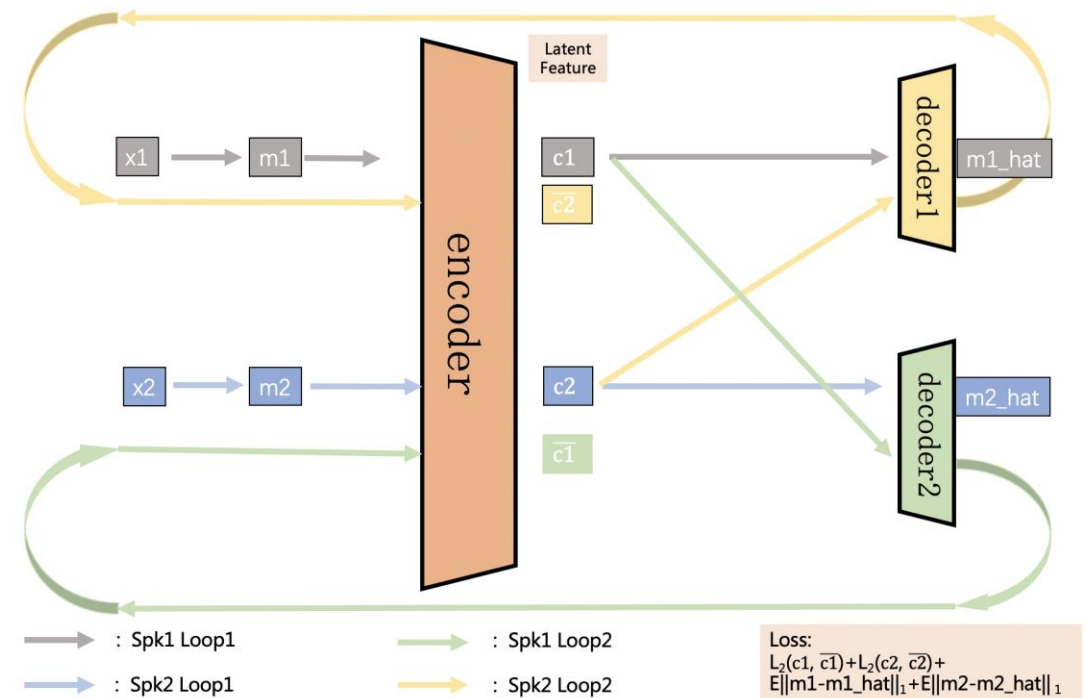
- **1st round encoding:** Firstly encode S^1 and S^2 , resulting in two sets of factors: $\mathbf{Z}^1 = \{\mathbf{Z}_r^1, \mathbf{Z}_f^1, \mathbf{Z}_c^1, \mathbf{Z}_t^1\}$ and $\mathbf{Z}^2 = \{\mathbf{Z}_r^2, \mathbf{Z}_f^2, \mathbf{Z}_c^2, \mathbf{Z}_t^2\}$.
- **Random factor substitution (RFS):** Randomly choose a factor from \mathbf{Z}^2 , and use it to replace the corresponding factor in \mathbf{Z}^1 . Suppose that the selected factor is \mathbf{Z}_f^2 , we get a new factor set $\mathbf{Z}' = \{\mathbf{Z}_r^1, \mathbf{Z}_f^2, \mathbf{Z}_c^1, \mathbf{Z}_t^1\}$.
- **Speech reconstruction:** Forward \mathbf{Z}' to the decoder and produce the reconstructed speech \hat{S}' .
- **2nd round encoding:** Encode \hat{S}' and obtain $\hat{\mathbf{Z}}' = \{\hat{\mathbf{Z}}_r', \hat{\mathbf{Z}}_f', \hat{\mathbf{Z}}_c', \hat{\mathbf{Z}}_t'\}$.
- The cycle loss is computed as: $\mathcal{L}_{cyc} = \|\mathbf{Z}' - \hat{\mathbf{Z}}'\|^2$
- The final loss: $\mathcal{L} = \mathcal{L}_{rec} + \alpha * \mathcal{L}_{cyc}$



Haoran Sun, Chen Chen, Lantian Li, Dong Wang, "CYCLEFLOW: PURIFY INFORMATION FACTORS BY CYCLE LOSS" in ICASSP 2021

Cycle loss based Exemplar Encoder

- **1st round encoding:** Firstly convert x_1 and x_2 into spectrum m_1 and m_2 ; encode into latent space. Save latent features as c_1 and c_2 .
- **Speech reconstruction:** Construct two decoders specific to speaker s_1 and s_2 . Forward c_1 and c_2 to the decoder and produce the reconstructed spectrum m_{1_hat} and m_{2_hat} .
- **2nd round encoding:** Forward c_1 and c_2 separate to decoder2 and decoder1; then encode through common encoder again for latent features \bar{c}_1 and \bar{c}_2



Loss:

$$L_{cycle} = L_2(c_1, \bar{c}_1) + L_2(c_2, \bar{c}_2)$$

$$L_{spec} = E\|m_1 - m_{1_hat}\|_1 + E\|m_2 - m_{2_hat}\|_1$$

$$L = \alpha * L_{cycle} + L_{spec}$$

Check latent code to verify a best encoder

- We extract the content code from the output of the encoder and use this code for a further test.
- First, we choose six phones from the same speaker of the training period, each of which consists of 6 samples.
- Then set these phones as input into the autoencoder, and we can get the latent codes of these phones.
- Use tSNE to observe the clustering capability of the phones. The dimension of the output of TSNE is 2.

50k iter



Theoretical Analysis

- Define $x_1 = \{c_1, s_1\}$ for a speech of Spk1, where c_1 refers to content and s_1 refers to style. Same for Spk2.
- In an autoencoder, a reconstruction process refers to $D(E(x))$
- For two encoders D_1 & D_2 specific for Spk1 and Spk2, further suppose $D_1(E(x_1)) = \widehat{x}_1$ for matched speech and decoder; $D_2(E(x_1)) = \overline{x}_1$ for mismatched speech and decoder.
- Then $\|x_1 - \widehat{x}_1\|^2 \rightarrow \|E(x_1) - E(\widehat{x}_1)\|^2 = \|c_1 - \widehat{c}_1\|^2 + \|s_1 - \widehat{s}_1\|^2$,
 - $\operatorname{argmin}_{\widehat{x}_1} \|x_1 - \widehat{x}_1\|^2 = \operatorname{argmin}_{\widehat{x}_1} \|D_1(E(x_1)) - \{c_1, s_1\}\|^2 = \{c_1, \widehat{s}_1\}$. When training decoder1 with Spk1 speech, we have $\widehat{s}_1 = s_1$, which means decoder1 has a manifold of s_1 .
 - $\operatorname{argmin}_{\widehat{x}_2} \|x_2 - \widehat{x}_2\|^2 = \operatorname{argmin}_{\widehat{x}_2} \|D_2(E(x_2)) - \{c_2, s_2\}\|^2 = \{c_1, \widehat{s}_2\}$. When training decoder2 with Spk2 speech, we have $\widehat{s}_2 = s_2$, which means decoder2 has a manifold of s_2 .
- While $\|x_1 - \overline{x}_1\|^2 \rightarrow \|E(x_1) - E(\overline{x}_1)\|^2 = \|c_1 - \overline{c}_1\|^2 + \|s_1 - \overline{s}_1\|^2$
 - $\operatorname{argmin}_{\overline{x}_1} \|E(x_1) - E(\overline{x}_1)\|^2 = \operatorname{argmin}_{\overline{x}_1} (\|c_1 - \overline{c}_1\|^2 + \|s_1 - \overline{s}_1\|^2) = \{c_1, s_1\}$
 - With cycle loss, we are training a weaker decoder at a compensate for a stronger encoder .

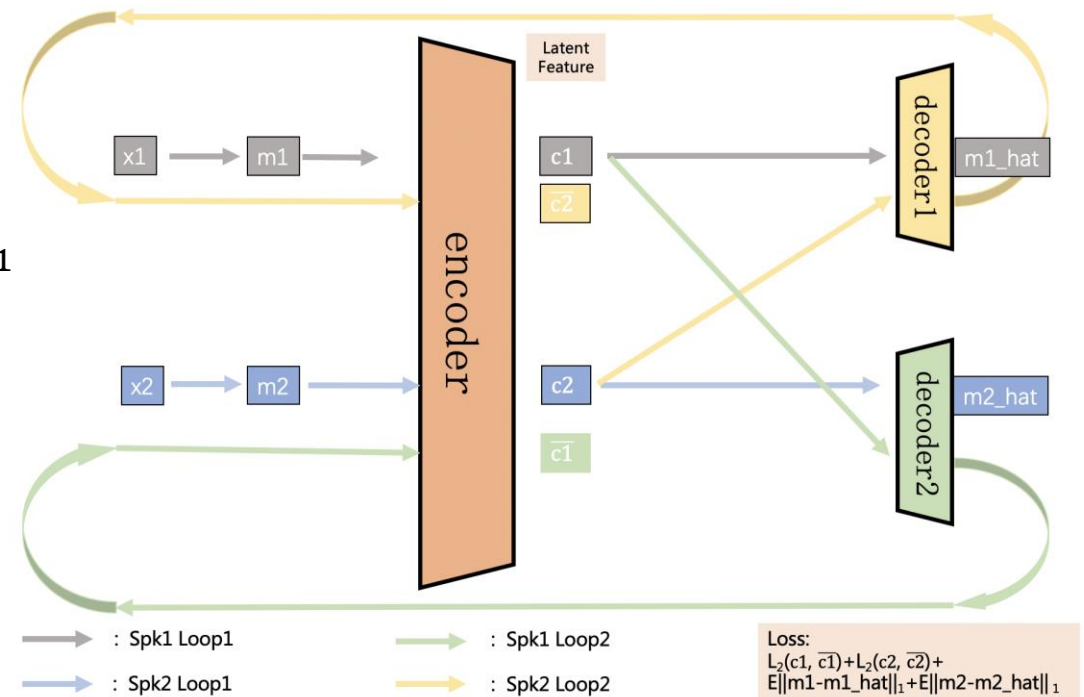
Multi-Step Training

- **1st step:** Introduce cycle loss for a stronger encoder.

Loss:

$$L_{cycle} = L_2(c1, \bar{c1}) + L_2(c2, \bar{c2})$$
$$L_{spec} = E||m1 - m1_{hat}||_1 + E||m2 - m2_{hat}||_1$$
$$L = \alpha * L_{cycle} + L_{spec}$$

- **2nd step:** Fix the encoder and finetune the decoder for an autoencoder for a specific speaker.



Dataset and Configurations

- Training: A male speaker and a female speaker in AIShell dataset.
 - Speech length: 24:26(male) 26:53(female)
- Test: 6 speakers in AIShell dataset.
- The speakers and utterances in the training and test sets are not overlapped.
- Use TSNE to select a qualified encoder for decoder finetune.

Experiments

- 1. A comparison between not finetuned models with cycle loss and without cycle loss.
- 2. A comparison between decoder-finetuned models with cycle loss and without cycle loss.

Not Finetuned Models (With Griffinlim)

• Original Speech

Baseline

With Cycle Loss

Without Cycle Loss



Conclusion1 : cycle-loss model does not have a better performance if not finetuned

Finetuned Models (With Wavenet)

• Original Speech



Baseline



With Cycle Loss



Without Cycle Loss



Conclusion2 : cycle-loss model has a better performance if finetuned

Conclusion and Prospect

- 1. We proposed an improved autoencoder with multi-step training based on cycle loss.
- 2. We demonstrated theoretically and empirically that multi-step training has a better performance on cross-gender issue, while the model without finetune cannot reach that performance.
- 3. The proposed model preserved the advantage of simplicity in baseline.
- Future work:
 - Test for different IB dimensions.
 - Test for multi-step training with more speakers